# Pulse/Data sensor (M-Bus/MiniBus)

For water gauge with HRI preparation

**AT 7275HRI** 

### Internet variants

# Range of application

HRI is an inductive universal sensor for remote reading/transfer of measurement values via M-bus, pulse or radio RF from water meter to data center or measurement systems. The sensor is compatible with Armatecs piston measuring chamber design type AT 7420, 7430, 7050. The unit is mounted on top of the meter's display board.

# HRI is available in 3 versions:

- HRI Data sensor is an electronic register with a data interface that supports both M-bus and portable Mini-bus equipment, e.g for reading the well meter (also see AT 7086). The sensor also has a programmable open collector pulse that is set at 1 liter per pulse when delivered.
- HRI Pulse transducer with reliable, high frequency pulse output of type open collector/ transistor relay. No drift due to telegraphing. Shielded against external magnetic fields. Compenses/indicates flow direction. The pulse is polarity dependent, which means that the connection cables must be connected to plus and minus respectively.
- HRI Radio scanner for radio systems, type scout. See product sheet AT 7087.



# **Quality assurance**

# CE-marking

The product is manufactured according to the requirements for electromagnetic compatibility in accordance with EEC Directive 98/34, European Standard EN61000-6-1.

# **Function and design**

The HRI device inductively reads the number of rotations on the metal indicator, located under the glass on the water meter's display board. The relation between the number of rotations and the read pointer is equal to D. D = number of liters per pulse and exists in different pulse numbers, eg 1, 10 and 100.

The HRI-unit has a built-in lithium battery for more than 10 years of operation. Measurement value and settings are maintained in case of power failure (e.g interference on the M-Bus loop). In case of power failure, the data-bus (M-bus/Minibus) will continue to register the values.

# **Technical data**

Cable lenght:	1,5m (does not apply to radio detectors)		
Protection:	IP 68 (Hermetically sealed)		
Storage temperature:	-20 °C to +65 °C		
Ambient temperature:	-10 °C to +65 °C		
Battery:	Lithium. Lifetime 10 +1 years (stockholding)		

Data interface	
Type:	M-bus och Mini-bus
Speed:	Automatic recognition, 300/2400 Baud
Protocol:	According to IEC 870 / EN 1434-3
	Measurement and measurement number (12 numbers as stand-
Data:	ard)
Max Cable lenght:	According to M-bus specifications

Measurement readings and settings remain in the event of any external power

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failure on the data receiver (e.g M-bus loop malfunctions). During power failure, the HRI-unit will continue to register the values.

Pulse output (I1, I2) enl. ISO/TC 30/SC 7/ WG 8				
Pulse type:	Open Collector, transistor relay (potential dependent)*			
Input voltage:	max 24 V			
Input current:	max 20 mA			
Input power:	max 0,48 VA			
Inner resistance:	100 Ohm			
Max. output frequency:	5 Hz; 124 ms pulse width			
Memory/storage:	up to 1 000 000 reversed pulses			
*To get a potential-free pulse, the AT 7281-2PCD must be mounted after the pulse sensor				

# **Accessories and options**

# Cable coupling, AT 7299IP68KAB:

As an accessory, there is a cable connection with protection class IP68 when you need to wire the cable to e.g a water-filled well.

# HRI Pulse encoder

- The output pulse (on the sensor indicated D..) is available with pulse rate: 1, 10, 100, 1000 liters per pulse. The pulse rate is permanently programmed from the factory. Sensors with pulse rate 10 are most common.
- Depending on the application, the HRI pulse encoder can be obtained in different models, but usually A4 is used. The function is illustrated in the following diagram.

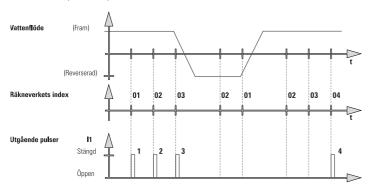
Rätten till ändringar utan föregående meddelande förbehålls. Amratec ansvaar rinte för eventuella tryckfel eller missförstånd. Dokumenten får kopieras endast i sin helhet.

# Pulse/Data sensor (M-Bus/MiniBus)

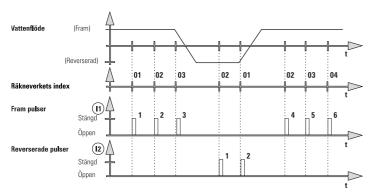
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### Mode A1/B1 (standard)



## Mode A2/B2



# Mode A3/B3 Vattenflöde (Fram) (Reverserad) Räkneverkets index 01 02 03 02 01 02 03 04 Fram och Reverserade pulser Stängd Öppen Flödesriktning (Reverserad) t t Framflöde Framflöde Framflöde

# HRI Data sensor

The data editor has an interface for reading measurement data and subsequent configuration. It also acts as an encoder with the ability to reprogramm the pulse count and the meter reading. Programming is done using PC-based service software MiniCom, via the M-bus loop and level converter, for example. AT 7530MR003USB.

# Programmable settings are:

- Performance B4
- Pulse rate (D)
- Meter, 12 numbers
- The counting start value (when the HRI-device is installed)

M-bus displays in standard version metrics with 8 digits with color display.

### Installation

The meter has to be prepared for HRI and an indicator equipped with a metal plate.

Before mounting the sensor, the transport foil on the underside of the sensor has to be removed.

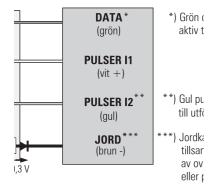
Assembly of the HRI-unit is done without the need to break any seals on the sensor, and this can be done either directly when the meter is mounted or afterwards when the meter already has been mounted.

The HRI-unit is screwed into place on the glass of the visor-glass in prepared attachment points with the supplied screws. Alternatively, the supplied attachment is used for sensor counter with copper/glass enclousre.

Adapted protective cover to the meter's display board is included for replacement.

The pulse encoder connection cable can be extended up to 50m, whereas the data wiring cable can be extended in accordance with the M-bus standard. Transient volt protection is recommended for outdoor wiring.

The HRI-unit is supplied with a four-wire connection cable as follows: M-bus, green and brown cable. Pulse, White (+) and brown (-) cable.



Cable	Туре	of HRI pulse output (A) / Data se	llse output (A) / Data sensor (B)	
	A4/B4 (standard)	A2/B2	A3/B3	
DATA (green)	M-bus* and Mini-bus	M-bus* and Mini-bus	M-bus* and Mini-bus	
I1 (white)	Balanced pulses**	Forward flow pulses	Forward-/backflow pulses	
l2 (vellow)	Manipulation/Error "normally closed"	Backflow pulses	Flow direction	

<sup>\*)</sup> External power supply can be supplied via the DATA cable: recommended 24 V DC (abs. max 50 V DC).

# Marking

The HRI-sensor is always labeled with the manufacturer's number, which for the data tuner corresponds to the secondary print. The data tuner is labeled with B4 by default. The encoder is by default marked with A4-D ...., where the number after D indicates the pulse weight in liters per pulse.

Fätten till ändringar utan föregående meddelande förbehålls. Amatec ansvaar rirte för eventuella tryckfel eller missförstånd. Dokurmenten får kopieras endast i sin helhet.

<sup>\*\*)</sup> Balanced pulses: Backflows must be compensated by identical forward flow before more pulses are taken out. This means that no output pulses are output during this period, even if the sensor counts forward.

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# How to order

Exampel: AT 7275HRI-A4-D10				
AT 7275HRI	-A4	-D10		
Fig. no.	Sensor type	D=Pulse number (liter/pulse)		
	A4=Pulse encoder	1 / 10 / 100 /1000 liters per pulse.		
	B4-D1=Datagivare (M-bus/Mini-bus, as well as programma-ble pulse)	(The data sensor is set to 1 lite rper pulse by default, D1)		